

Actions

mc: move clockwise

mac: move anticlockwise

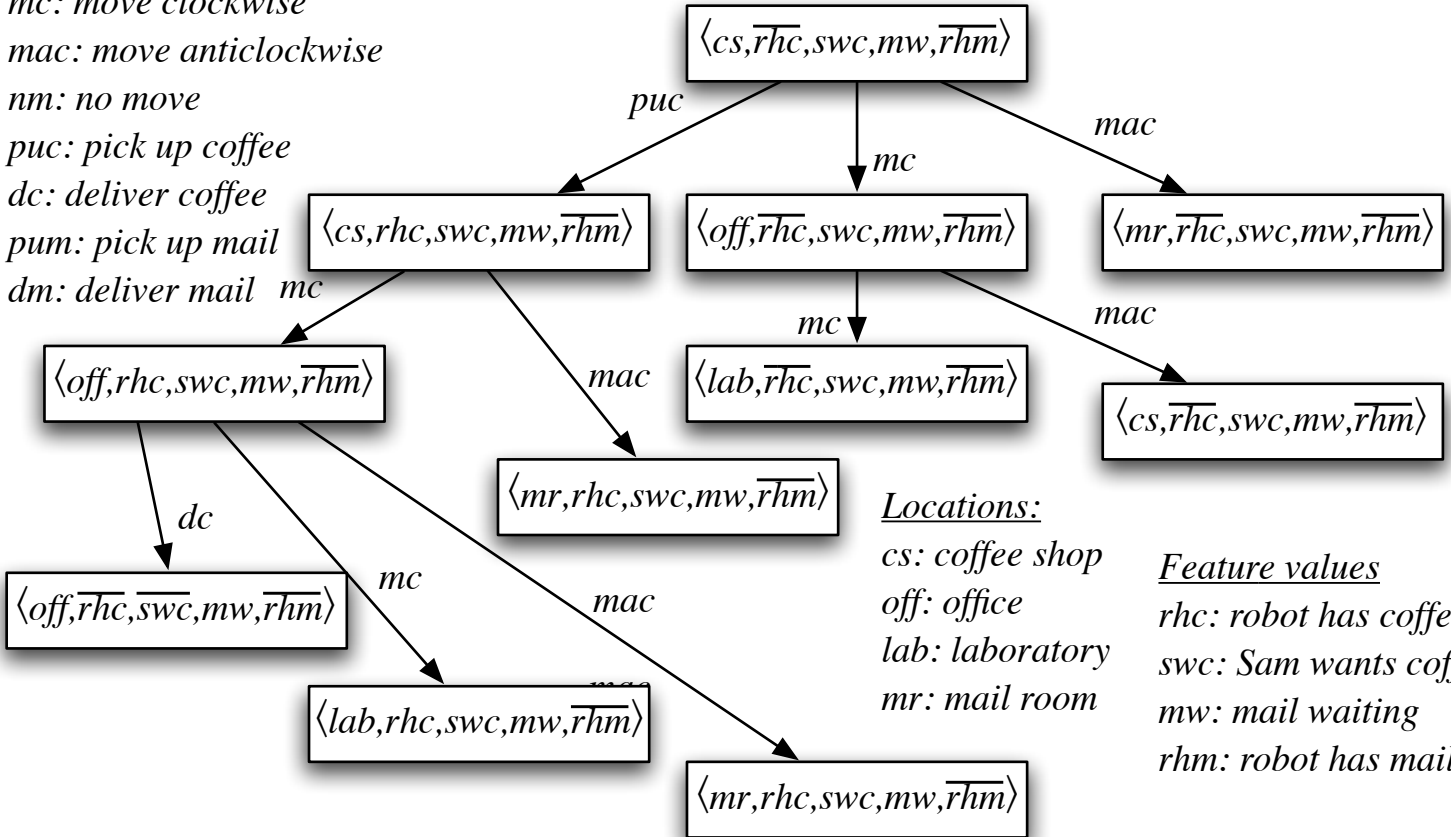
nm: no move

puc: pick up coffee

dc: deliver coffee

pum: pick up mail

dm: deliver mail



Locations:

cs: coffee shop

off: office

lab: laboratory

mr: mail room

Feature values

rhc: robot has coffee

swc: Sam wants coffee

mw: mail waiting

rhm: robot has mail